MPC-2042

2-AXIS MOTION CONTROL CARD

USER'S MANUAL (V1.0)

健昇科技股份有限公司

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Correction record

Version	Record
1.0	For driver 1.0 up

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Notes on hardware installation

Please follow step by step as you are installing the control cards.

1. Be sure your system is power off.
2. Be sure your external power supply for the wiring board is power off.
3. Plug your control card in slot, and make sure the golden fingers are put in right contacts.
4. Fasten the screw to fix the card.
5. Connect the cable between the card and wiring board.
6. Connect the external power supply for the wiring board.
7. Recheck everything is OK before system power on.
8. External power on.

Congratulation! You have it.

1. Forward

Thank you for your selection of 2 axis motion control card. This card adopt the ASIC chip with complex motion functions including point to point, linear and circular interpolation, linear and s-curve acceleration/deceleration and several miscellaneous functions. Dll's of various functions will save you a lot of time in the motion related projects.

Our other motion control products:
MPC-2004 4 axes point to point motion control card (ISA bus)
MPC-3004 4 axes linear / point to point motion control card (PCI bus)
MPC-3024 4 axes linear/circular/point to point (standard function) motion control card (PCI bus)
MPC-3034 4 axes linear/circular/point to point (standard function) motion control card (PCI bus)
MPC-3028 8 axes linear/circular/point to point (standard function) motion control card (PCI bus)

Any comment is welcome,
please visit our website
http:// www.automation.com.tw for the up to date information.

2. Features

Main card

2.1 2-axis servo/stepping motor control
2.2 2 28-bit up/down counter for incremental encoder
2.3 2 28-bit up/down counter for pulse handler input
2.4 Pulse output rate up to 6.55MHz
2.5 Pulse output options : OUT/DIR,CW/CCW
2.6 linear interpolation
2.7 circular interpolation
2.8 Continuous interpolation
2.9 Speed change on-the-fly
2.10 Motion parameters change on the fly
2.11 Position latch function
2.12 Programmable acceleration/deceleration time
2.13 Linear and S-curve acceleration curve
2.14 Simultaneously start/stop on multi-axes
2.15 Backlash compensation
2.16 Software limit switches protection

Wiring board

DIN RAIL MOUNTED WIRING BOARD
2.19 25 pin D-type connector to wiring terminals for JM3 pulse handler interface
2.20 68 pin SCSI connector to wiring terminals for JF2 motion control interface
2.21 ADP-9201DIN for JM1 isolated digital I/O interface

3. Specifications

3.1 Main card

Motion

3.1.1. Max pulse rate — 6,553,500 pps

3.1.2. Pulse output mode — Single phase: CLOCK,DIR

3.1.3. Dual phase: CW, CCW

3.1.4. Acceleration / Deceleration mode — linear ,S-curve mode

3.1.5. Homing mode — 14 types

3.1.6. Encoder up/down counter — 2 28bit counter

3.1.7. Pulse Handle up/down counter — 2 28 bit counter

3.1.8. Linear interpolation

3.1.9. Circular interpolation

Digital I/O

3.1.10. Motion specific input — SRDY,ALM,LS+,LS-,SD,ORG(Home),PCS,LTC,INP STA per axis, EMG per card

3.1.11. Motion specific output — CMP,SVON,ERC,FIN per axis

3.1.12. General input — 8 bit, photo isolated

3.1.13. General output — 8 bit, photo isolated

3.1.14. TTL I/P — 8 bits

General

3.1.15. Insulation resistance— 100 MΩ (min) at 1000Vdc

3.1.16. Isolation voltage— 2500Vac 1Min

3.1.17. I/O connector — 68pin female scsi connector

3.1.18. External supply — DC 24±4V

3.1.19. Operation temperature— 0 to 70° C

3.1.20. Storage temperature— -20 to 80° C

3.1.21. Operation humidity— 5~95% RH, non-condensing

3.1.22. Dimensions— 175(W) ×110(H) mm

3.2 DIN rail wiring board

For JF2 motion control interface

3.2.1. Connection cable — SCSI-II 68 pin cable to connect main and wiring board

3.2.2. Dimension — 85(W)*192(L)*52(H)mm

For JM3 pulse handler interface

3.2.3. Connection cable — D-type 25P cable to connect main and wiring board

3.2.4. Dimension — 85(W)*80(L)*52(H)mm

For JM1 isolated digital I/O

3.2.5. Connection cable — 20P flat cable to connect main and wiring board

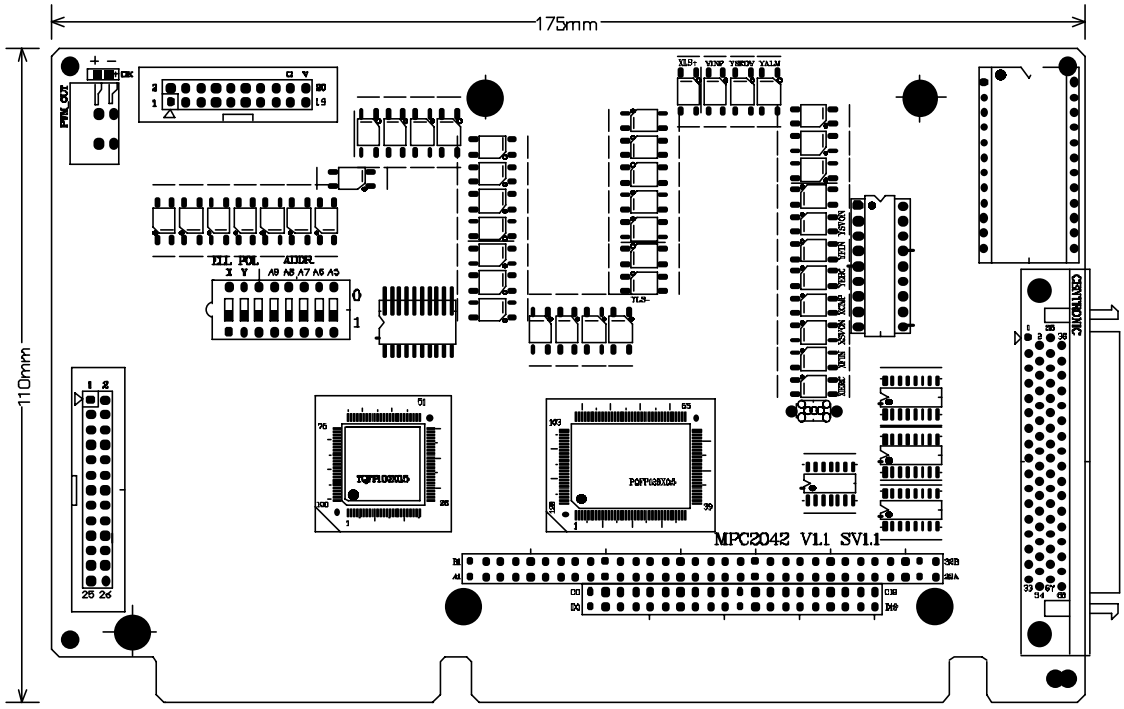
3.2.6. Dimension — 85(W)*103(L)*43(H)mm (for relay/PMOS type wiring board)
— 85(W)*103(L)*50(H)mm (for SSR type wiring board)

3.2.7. indicators — LED, power x 1, digital input x 8, digital output x8

3.2.8. output rating — 3A @250Vac,30Vdc (relay)
1A @24Vdc (PMOS)
2A @240Vac(SSR)

4. Dimension and Layout

4.1 MPC2042 Main Card Layout



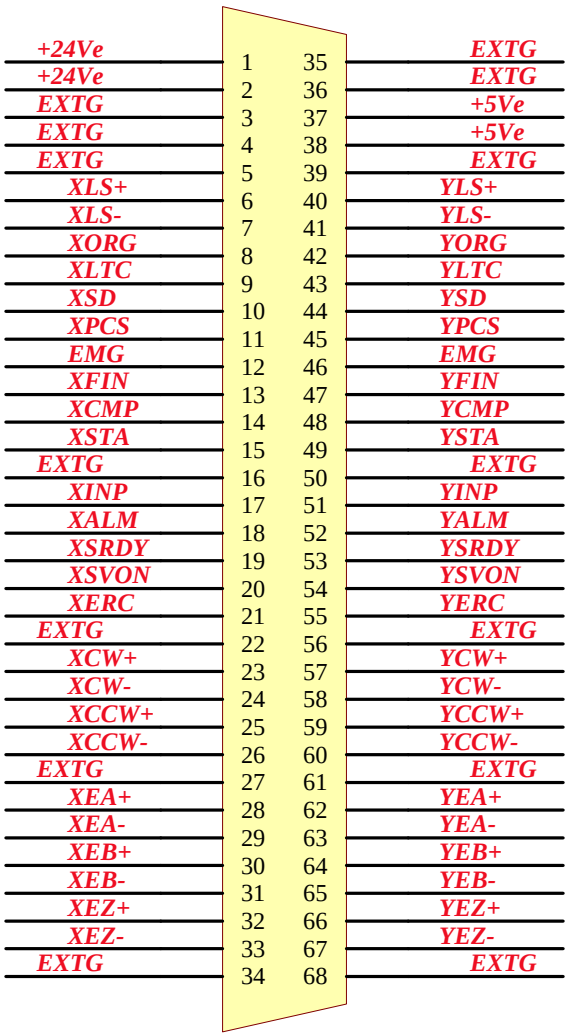
5. Pin Definitions

5.1 JF1 Assignment / Definitions

Pin	Definition
+	PWM DA output +
-	PWM DA output - (ground)

5.2 JF2 Assignment / Definitions

JF2


+24Ve 1 35 EXTG
+24Ve 2 36 EXTG
EXTG 3 37 +5Ve
EXTG 4 38 +5Ve
EXTG 5 39 EXTG
XLS+ 6 40 YLS+
XLS- 7 41 YLS-
XORG 8 42 YORG
XLTC 9 43 YLTC
XSD 10 44 YSD
XPCS 11 45 YPCS
EMG 12 46 EMG
XFIN 13 47 YFIN
XCMP 14 48 YCMP
XSTA 15 49 YSTA
EXTG 16 50 EXTG
XINP 17 51 YINP
XALM 18 52 YALM
XSRDY 19 53 YSRDY
XSVON 20 54 YSVON
XERC 21 55 YERC
EXTG 22 56 EXTG
XCW+ 23 57 YCW+
XCW- 24 58 YCW-
XCCW+ 25 59 YCCW+
XCCW- 26 60 YCCW-
EXTG 27 61 EXTG
XEA+ 28 62 YEA+
XEA- 29 63 YEA-
XEB+ 30 64 YEB+
XEB- 31 65 YEB-
XEZ+ 32 66 YEZ+
XEZ- 33 67 YEZ-
EXTG 34 68 EXTG

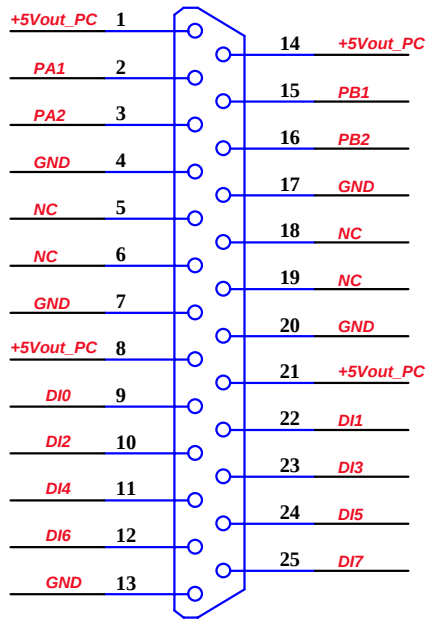
SCSI68PF-90_CENTRONIC

PIN	I/O	Descriptions	PIN	I/O	Descriptions
1	I	+24V External DC24V power input	35	I	EXTG Common for external power (+24V and +5V)
2	I	+24V External DC24V power input	36	I	EXTG Common for external power (+24V and +5V)
3	I	EXTG Common for external power (+24V and +5V)	37	O	+5Ve Output of on board DC/DC converter
4	I	EXTG Common for external power (+24V and +5V)	38	O	+5Ve Output of on board DC/DC converter
5	I	EXTG Common for external power (+24V and +5V)	39	I	EXTG Common for external power (+24V and +5V)
6	I	XLS+ Positive over travel LS input of X axis	40	I	YLS+ Positive over travel LS input of Y axis
7	I	XLS- Negative over travel LS input of X axis	41	I	YLS- Negative over travel LS input of Y axis
8	I	XORG (XHOME) Origion (Home) LS input of X axis	42	I	YORG (YHOME) Origion (Home) LS input of Y axis
9	I	XLTC Latch counter trigger input of X axis	43	I	YLTC Latch counter trigger input of Y axis
10	I	XSD Slowdown LS input of X axis	44	I	YSD Slowdown LS input of Y axis
11	I	XPCS Position change start signal input of X axis	45	I	YPCS Position change start signal input of Y axis
12	I	EMG Emergency stop, stop all axes	46	I	EMG Emergency stop, stop all axes
13	O	XFIN General purpose output of X axis	47	O	YFIN General purpose output of Y axis
14	O	XCMP General out or compare out of X axis	48	O	YCMP General out or compare out of Y axis
15	I	XSTA Start motion signal input for X axis	49	I	YSTA Start motion signal input for Y axis
16	I	EXTG Common for external power (+24V and +5V)	50	I	EXTG Common for external power (+24V and +5V)
17	I	XINP General I/p of X axis	51	I	YINP General I/p of Y axis
18	I	XALM ALARM I/p of X axis	52	I	YALM ALARM I/p of Y axis
19	I	XSRDY Servo Ready signal of X axis	53	I	YSRDY Servo Ready signal of Y axis
20	O	XSVON Servo on of X axis	54	O	YSVON Servo on of Y axis
21	O	XERC Output for resetting error counter of X axis	55	O	YERC Output for resetting error counter of Y axis
22	I	EXTG Common for external power (+24V and +5V)	56	I	EXTG Common for external power (+24V and +5V)
23	O	XCW+ CW+ or PULSE+ of X axis	57	O	YCW+ CW+ or PULSE+ of Y axis
24	O	XCW- CW- or PULSE- of X axis	58	O	YCW- CW- or PULSE- of Y axis
25	O	XCCW+ CCW+ or DIR+ of X axis	59	O	YCCW+ CCW+ or DIR+ of Y axis
26	O	XCCW- CCW- or DIR- of X axis	60	O	YCCW- CCW- or DIR- of Y axis
27	I	EXTG Common for external power (+24V and +5V)	61	I	EXTG Common for external power (+24V and +5V)
28	I	XEA+ Encoder phase A+ feedback of X axis	62	I	YEA+ Encoder phase A+ feedback of Y axis
29	I	XEA- Encoder phase A- feedback of X axis	63	I	YEA- Encoder phase A- feedback of Y axis

30	I	XEB+ Encoder phase B+ feedback of X axis	64	I	YEB+ Encoder phase B+ feedback of Y axis
31	I	XEB- Encoder phase B- feedback of X axis	65	I	YEB- Encoder phase B- feedback of Y axis
32	I	XEZ+ Encoder phase Z+ feedback of X axis	66	I	YEZ+ Encoder phase Z+ feedback of Y axis
33	I	XEZ- Encoder phase Z- feedback of X axis	67	I	YEZ- Encoder phase Z- feedback of Y axis
34	I	EXTG Common for external power (+24V and +5V)	68	I	EXTG Common for external power (+24V and +5V)

5.3 JM3 Assignment / Definitions

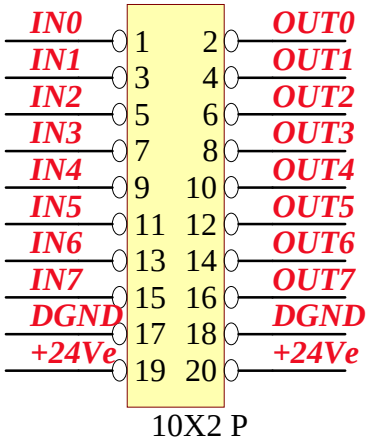
PIN	Description
1	+5V from PC
2	Pulse handler1 A phase input
3	Pulse handler2 A phase input
4	GND
5	NC
6	NC
7	GND
8	+5V from PC
9	TTL I/P bit0
10	TTL I/P bit2
11	TTL I/P bit4
12	TTL I/P bit6
13	GND



PIN	Description
14	+5V from PC
15	Pulse handler1 B phase input
16	Pulse handler2 B phase input
17	GND
18	NC
19	NC
20	GND
21	+5V from PC
22	TTL I/P bit1
23	TTL I/P bit3
24	TTL I/P bit5
25	TTL I/P bit7

5.4 JM1 Assignment / Definitions

PIN	DESCRIPTIONS
1	IN0: input0
3	IN1: input1
5	IN2: input2
7	IN3: input3
9	IN4: input4
11	IN5: input5
13	IN6: input6
15	IN7: input7
17	DGND:digital ground (EXTG)
19	+24Ve: external input power supply



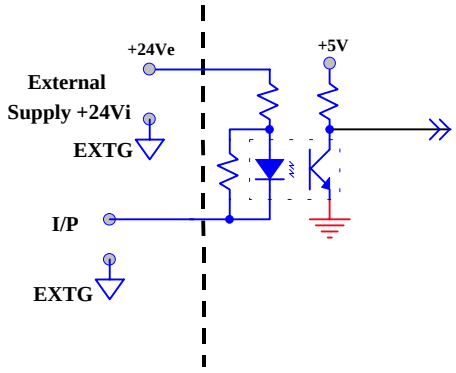
PIN	DESCRIPTIONS
2	OUT0:output0
4	OUT1:output1
6	OUT2:output2
8	OUT3:output3
10	OUT4:output4
12	OUT5:output5
14	OUT6:output6
16	OUT7:output7
18	DGND:digital ground (EXTG)
20	+24Ve: external input power supply

6. I/O Interface Diagram

6.1 Input Diagram

Type 1 input:

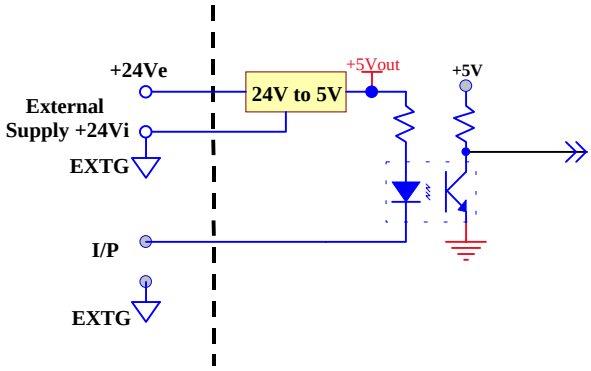
Wiring board Main card



For input: LS+,LS-,SD,ORG,PCS,LTC,STA,EMG
IN0~IN7

Type 2 input:

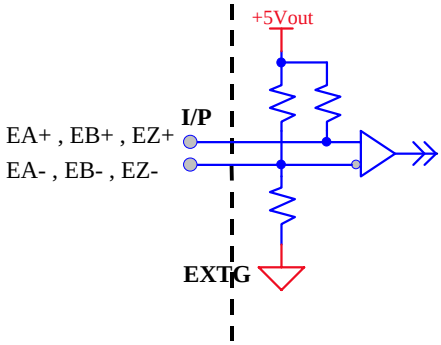
Wiring board Main card



For input: INP,SRDY,ALM

Type 3 input:

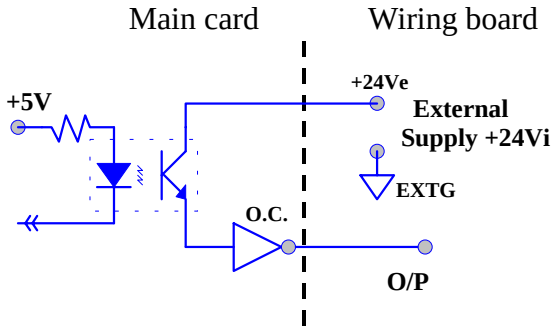
Wiring board Main card



For encoder feedback input.

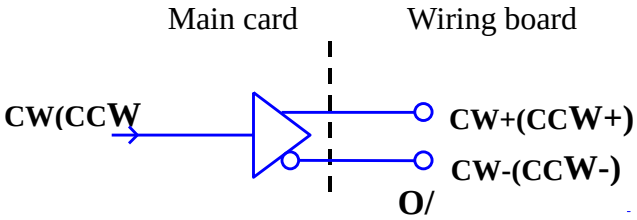
6.2 Output Diagram

Type1 output:



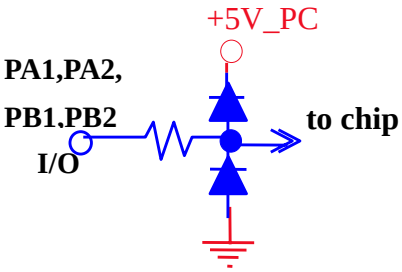
For OUT0 ~ OUT7

Type 2 output:



For motion control pulse output

6.3 Pulse Handler Input Diagram



7. HARDWARE SETTINGS

7.1 Card Address Setting

Refer to sec. 4.1 main card layout, the DIP SW for I/O base address setting.

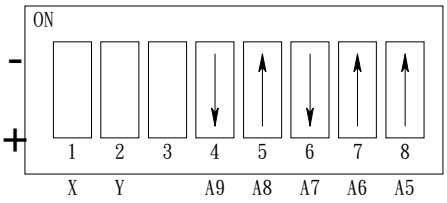
There are 16 locations occupied by MPC2042 card.

The DIP#1 for A9，DIP#2 for A8，and so forth. DIP switch upside mean “0”, and down side means “1”.

For example, to set I/O address at 280H:

DIP#4	DIP#5	DIP#6	DIP#7	DIP#8
A9	A8	A7	A6	A5
1	0	1	0	0

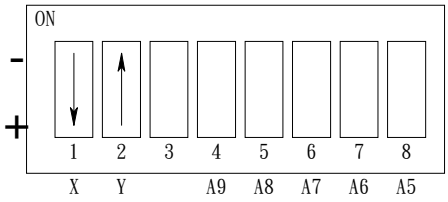
DIP SW SETTING：(280H)



7.2 POLARITY SETTING FOR OVER-TRAVEL LIMIT SWITCH

For different applications maybe you have different considerations, the polarity of over-travel limit switch can be set by on card Dip switch to meet your requirement.

Say X axis polarity is positive and Y axis polarity is negative.



8. APPLICATIONS

Precision positioning control
Precision speed control
Contouring control
X-Y table control
Rotary machine control
Robotic control
Biotech sampling and handling
Any combined control of servo and stepping motors

9. Ordering Information

PRODUCT	DESCRIPTIONS
MPC2042	2-axis motion control card for servo/step motor control (include SM23404)
MPC2042P	2-axis motion control card for servo/step motor control (include SM23404) with PC104 socket
JD50095	DIN rail mounted dummy wiring board for JF2
JS51050	DIN rail mounted dummy wiring board for JM3
ADP-9201DIN(R)	DIN rail mounted wiring board with 16 I/O LED indicators and relay output for 8DI and 8DO (for JM1)
ADP-9201DIN(P)	DIN rail mounted wiring board with 16 I/O LED indicators and PMOS output for 8DI and 8DO (for JM1)
ADP-9201DIN(S)	DIN rail mounted wiring board with 16 I/O LED indicators and SSR output for 8DI and 8DO (for JM1)
FVC01	Frequency to voltage module
M266868154	68-pin SCSI cable 1.5M
M266868302	68-pin SCSI cable 3.0M
M270325X4	D type 25p male-female cable 1.8M
M270325X0	D type 25p male-female cable 3.0M
M23207	20 pin flat cable 1.5M
M23209	20 pin flat cable 3.0M
SM23404	Extension kit for JM3 (bracket and flat cable for 25p D-type connector)